

# A Method for Solving Poisson Problems

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# The Electrostatic Potential

In this work, we are developing a stable, accurate, and fast method for calculating the electrostatic potential on a grid. We calculate it by using the operator solution to the Poisson equation:

$$V(\mathbf{x}) = \frac{2\pi\hbar^2}{m_0} \hat{T}^{-1} \rho_0(\mathbf{x})$$

$\rho_0(\mathbf{x})$ : charge distribution  
 $\hat{T}$ : the kinetic energy operator for a fictitious particle of mass  $m_0$

Using the identity  $\hat{T}^{-1} = \int_0^\infty d\beta e^{-\beta\hat{T}}$  we obtain

$$V(\mathbf{x}) = \int_0^\infty d\beta \int_{\mathbb{R}^3} d\mathbf{x}' \langle \mathbf{x} | e^{-\beta\hat{T}} | \mathbf{x}' \rangle \psi_0(\mathbf{x}')$$

$$\psi_0(\mathbf{x}) \equiv \frac{2\pi\hbar^2}{m_0} \rho_0(\mathbf{x})$$

# The Integration Technique

For the integral over  $\mathbb{R}^3$

C. Predescu, *J. Theor. Comp. Chem.* 5:255, 2006.

$$\psi_\tau(x, y, z) = \sum_{j_x, j_y, j_z = -1}^1 w_{j_x}^h w_{j_y}^h w_{j_z}^h \psi_0(x + j_x \Delta, y + j_y \Delta, z + j_z \Delta)$$

$$\Delta = h\sigma \quad h = \sqrt{3} \quad w_{-1}^h = w_1^h = 1/6 \quad w_0^h = 2/3$$

For the integral over  $\beta$

$$\begin{aligned} V(\mathbf{x}) &= \int_0^\tau d\beta \psi_\beta(\mathbf{x}) + \int_\tau^\infty d\beta \psi_\beta(\mathbf{x}) \\ &= \int_0^\tau d\beta \psi_\beta(\mathbf{x}) + \left( e^{-\tau \hat{T}} V \right) (\mathbf{x}) \end{aligned}$$

$$\psi_\beta(\mathbf{x}) = \int_{\mathbb{R}^3} d\mathbf{x}' \left\langle \mathbf{x} \left| e^{-\beta \hat{T}} \right| \mathbf{x}' \right\rangle \psi_0(\mathbf{x}')$$

# Features of the technique

- This technique is stable (positive charge distributions will produce positive potentials at all levels of approximation).
- Because of the iterative nature of this technique, we can use an initial guess potential instead of the initial charge distribution in order to speed up the computation.
- We also avoid the need for excessively large grids by using Beck's suggestion to calculate the potential on the frontier exactly.
- The technique is parallelizable on distributed memory machines with preservation of scaling (domain decomposition).

# Discrete Charge Distributions

To test this technique, several discrete charge distributions have been used. A simple monopole, with charge  $+1.0$ , is the first example. Because the  $1/r$  fall-off of the monopole potential is extremely slow, this is expected to be the worst-case scenario for this technique.

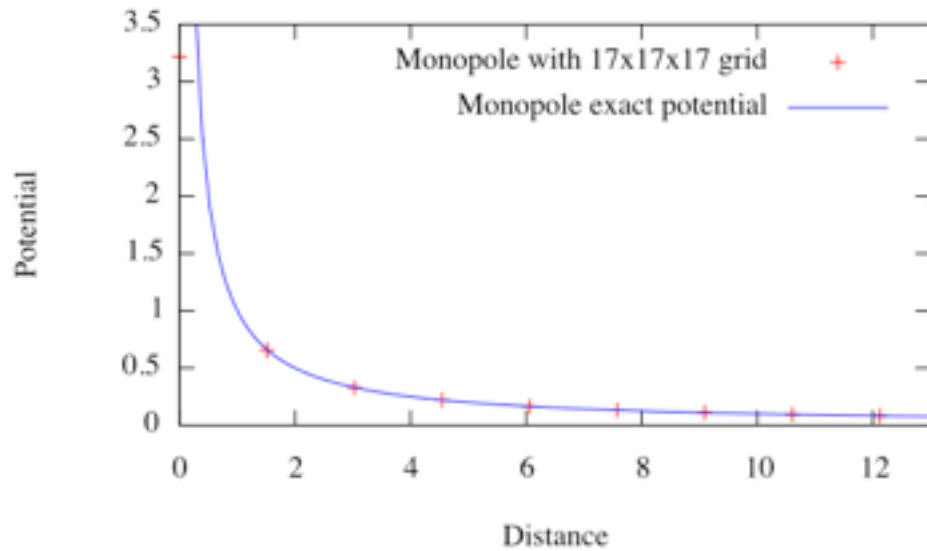
Dipoles have also been studied, with unit charges of opposite sign separated by  $2.0$  units of distance. Larger separations were also explored with essentially the same results.

Finally, a quadrupole with a positive central charge ( $+2.0$ ) and negative unit charges at  $1.0$  units from the center was studied.

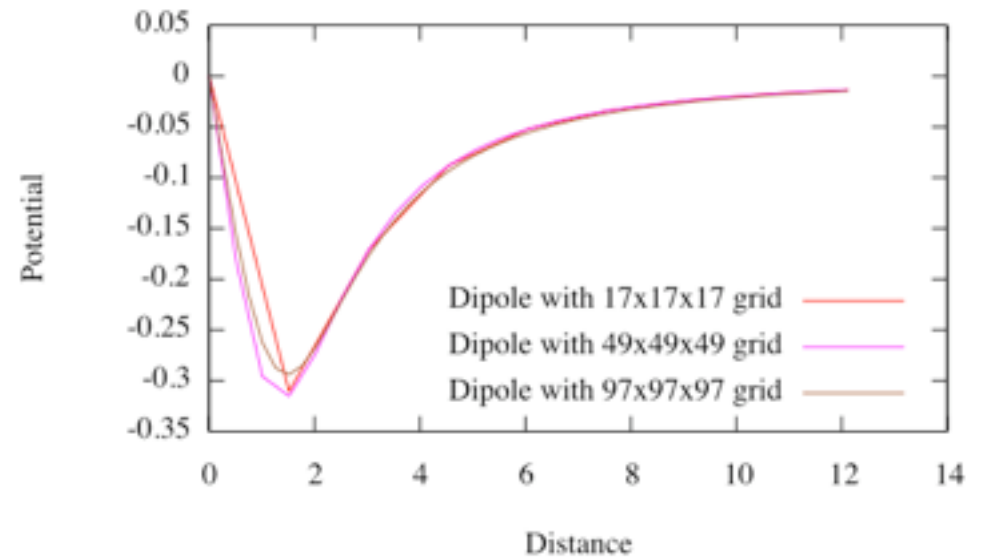
All of these systems were studied in a cube with side length  $15.0$  units, with  $17^3$ ,  $33^3$ ,  $49^3$ ,  $65^3$ ,  $81^3$ , and  $97^3$  total gridpoints.

# Accuracy of the Technique

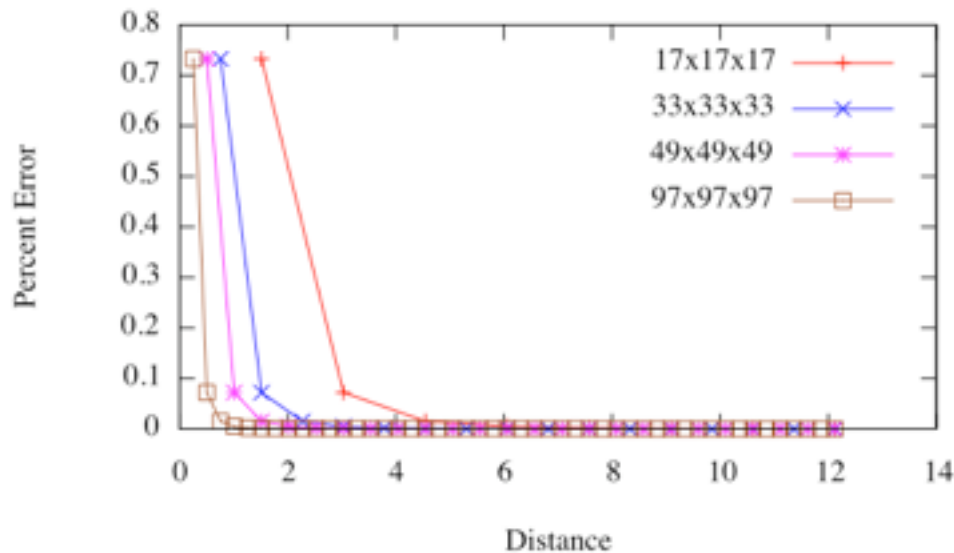
Calculated vs. Exact Potential



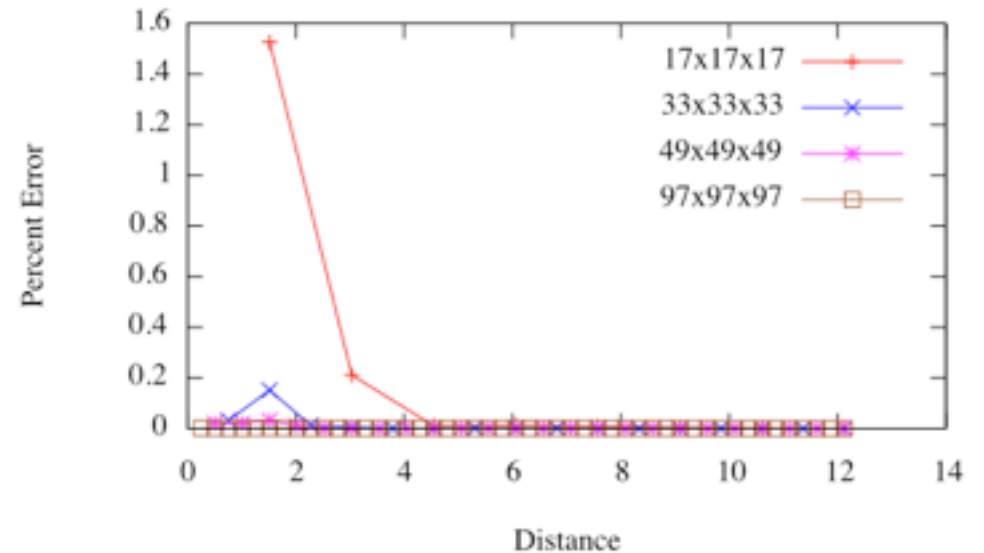
Calculated vs. Exact Potential



Percent Error By Grid Size (for monopole)

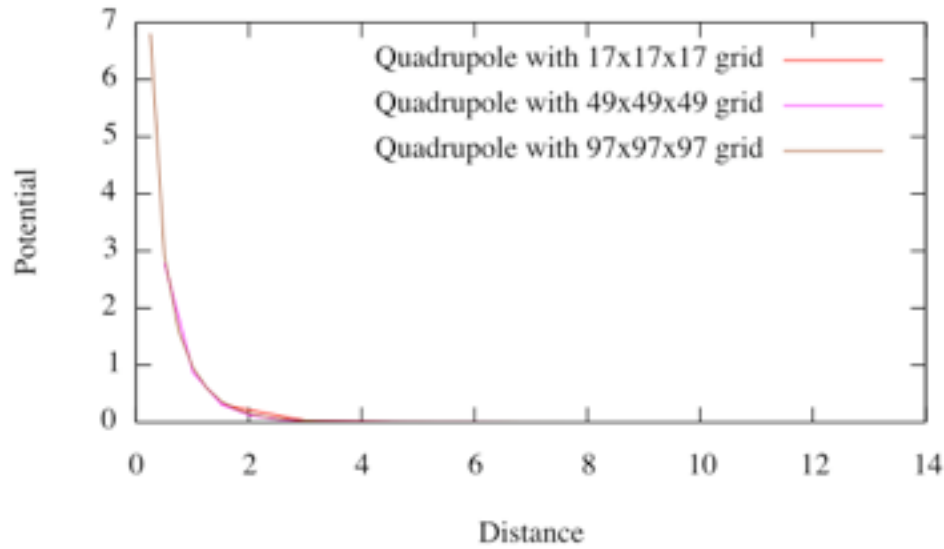


Percent Error By Grid Size (for dipole)

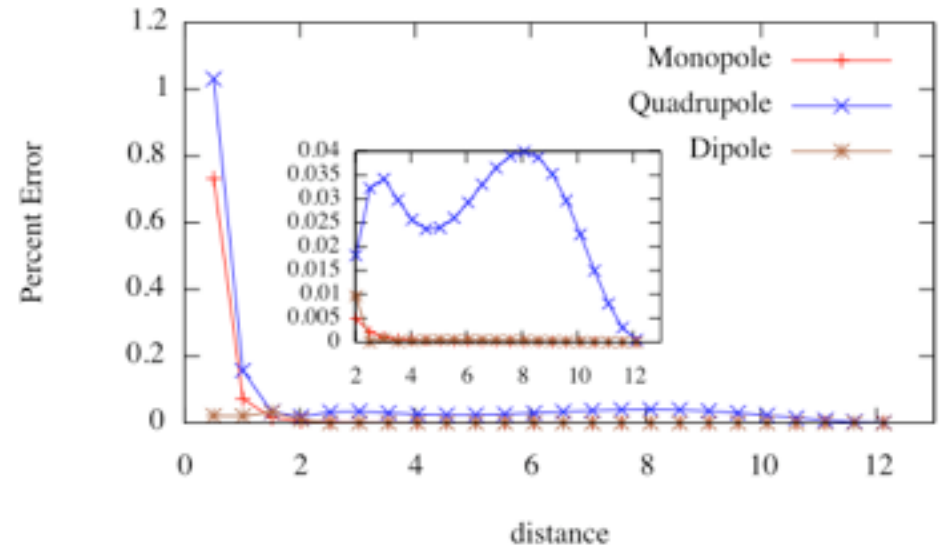


# Accuracy

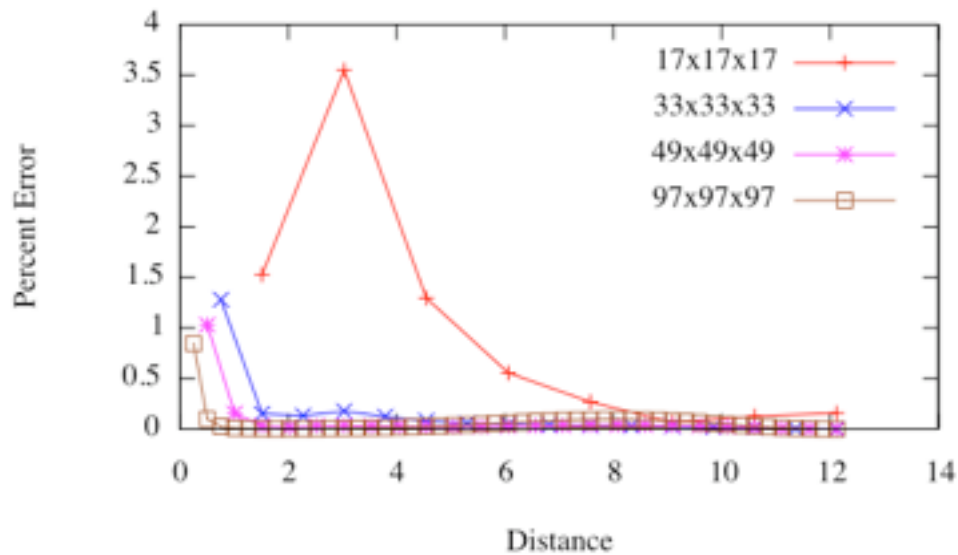
Calculated vs. Exact Potential



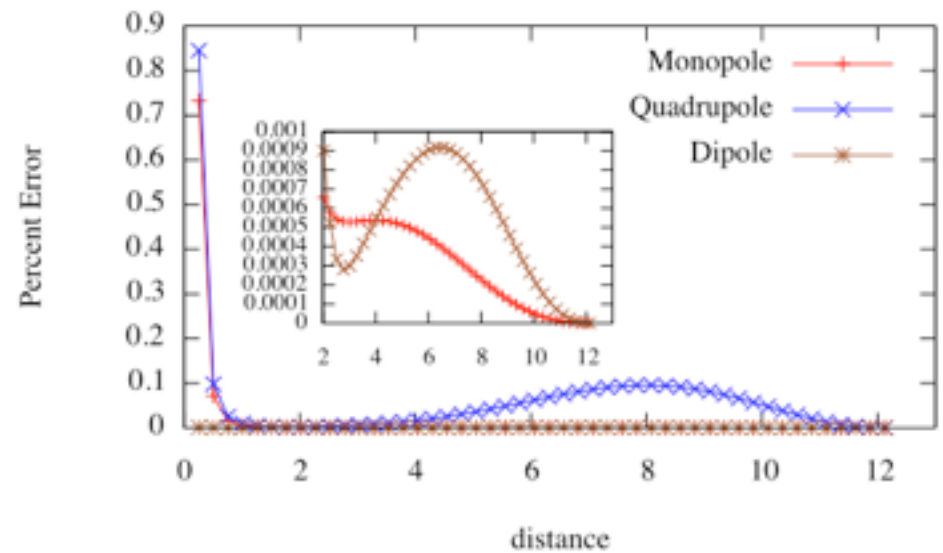
Percent Error By System, Grid Size 49x49x49



Percent Error By Grid Size (for quadrupole)

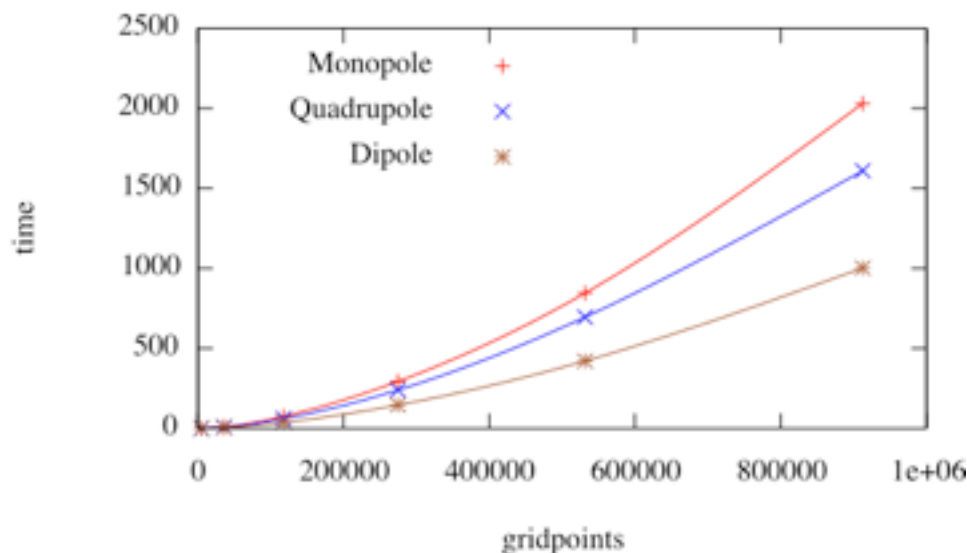


Percent Error By System, Grid Size 97x97x97



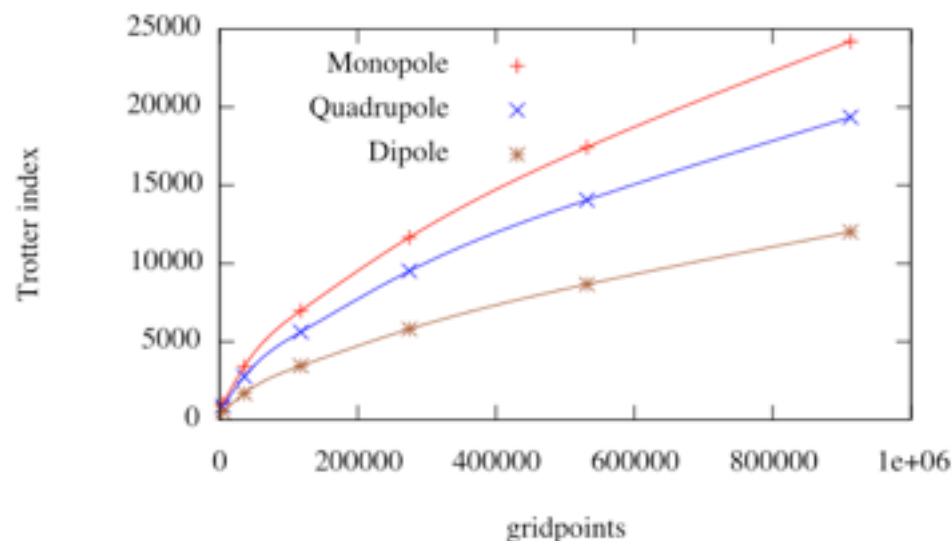
# Timing of the Technique

Scaling of the Trotter Time



The timing of this technique has been explored in what is expected to be the worst case scenario. The “guess” potential is set to the charge distribution. The convergence criterion was a maximum change of  $10^{-8}$  over ten Trotter steps.

Scaling of the Trotter Index



Both the Trotter iteration and the calculation of the exact values on the frontier take  $O(n^{5/3})$  time. However, the calculation of the frontier (naïvely implemented) takes 2 or 3 times as long as the Trotter iteration (converging to  $10^{-8}$ ) in measured CPU time.

As expected, the monopole gives the slowest convergence, because of its long-range effects. The dipole converges fastest.



# Future Directions

- Application of fourth-order integration techniques for improved accuracy
- Use of guess potentials to decrease number of iterations required for convergence
- Explore use of multigridding with this technique
- This technique is a step in a larger project to use the density matrix formalism for linearly scaling electronic structure calculations

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